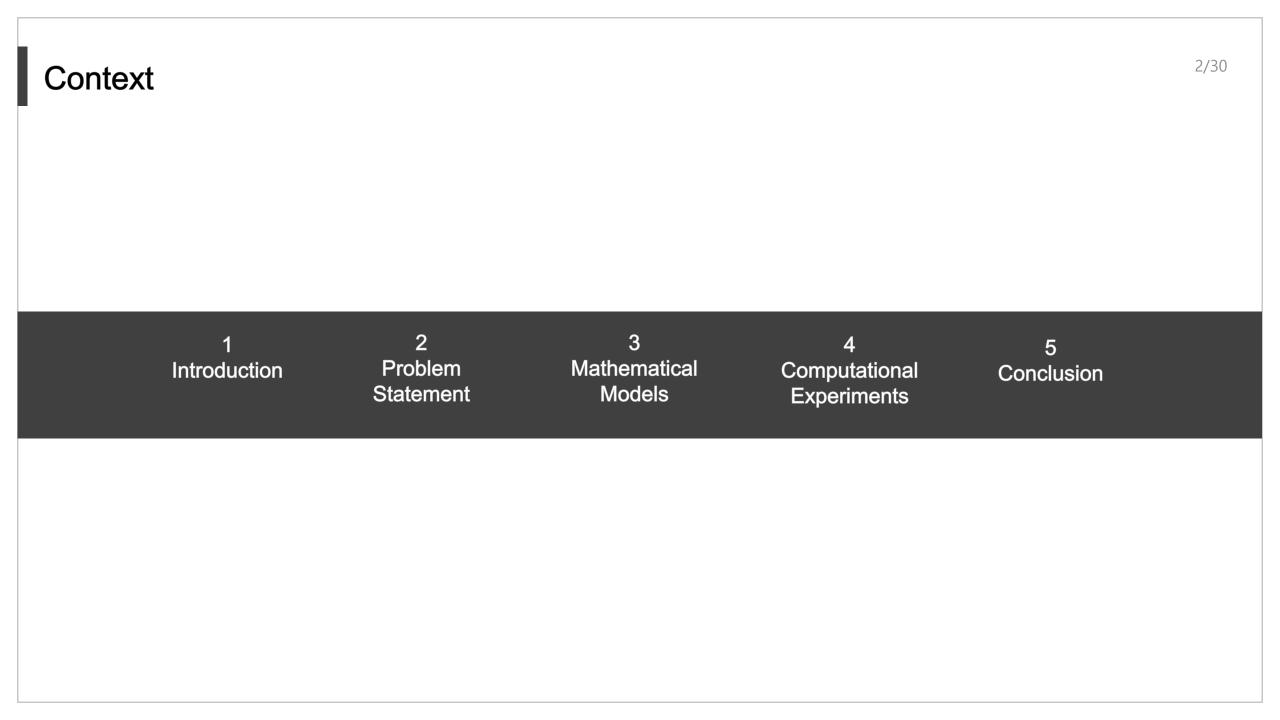
# Strategic bundling approach for gig economy operation of electric scooter recharging

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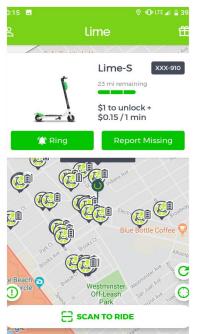




# 1. Introduction

# Electric scooter sharing service

### First mile-last mile transportation

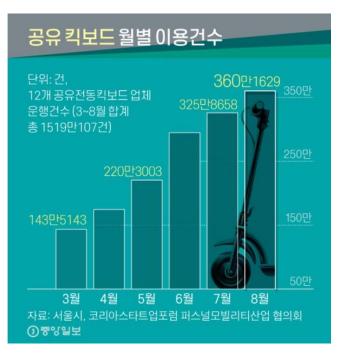




 $\rightarrow$  **Dockless**: No designated station for pick-up and return

 $\rightarrow$  Convenient for short-distance travel connecting transportation hubs

### Increase in usage due to COVID-19



 $\rightarrow$  The number of usage has increased by more than **4.3 times** compared to the second half of last year

Mobility as a service(MaaS) for daily, non-face-to-face, micro transportation

# Motivation Introduction(2/5)

### Gig economy



 $\rightarrow$  Free market system where organizations and independent workers engage in temporary or short-term work arrangements via platform



- ✓ Self-regulated
- ✓ Contingent
- ✓ Individual stakeholders

### Lime juicer





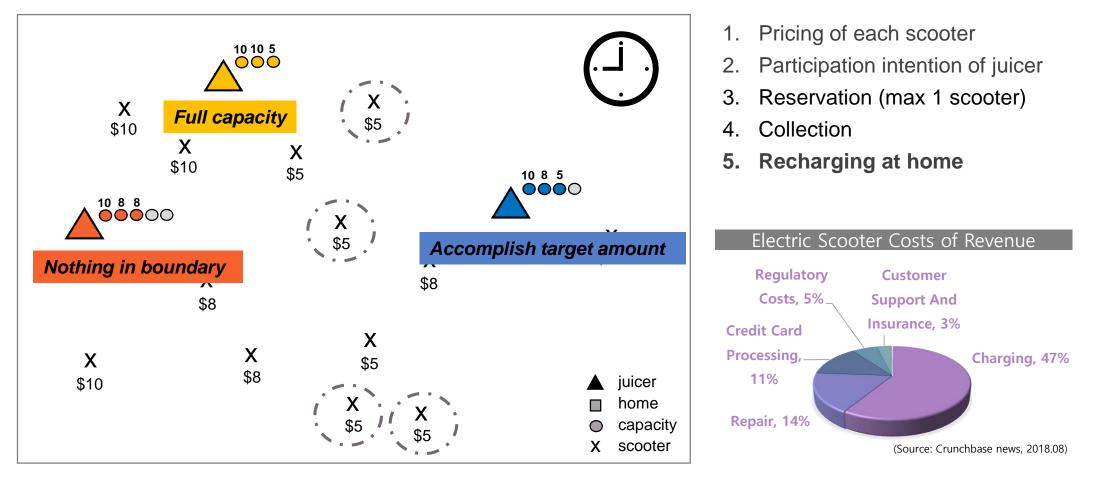
→ Network of independent contractors who collect and charge electric kickboards every night and redeploy them in the morning.

### $\rightarrow$ Collection Price

	USA	KOREA
Price	\$5~\$12 (\$8 avg)	₩3,000~₩4,000
Max. Price	\$20	₩6,000

# Juicer System Introduction(3/5)

# Lime's charging strategy with juicer



Collection rate: 9/13

# Literature Review

Introduction(4/5)

# E-scooter recharging operation

- Hub station design for e-scooters
   Goshtasb (2018). San Jose State University Graduate Research
  - Violates the dockless system
- E-scooter assignment problem
   Masoud et al. (2019) : *IEEE Access* 7
  - → Allow company's intervention to chargers
- Stochastic model for e-scooter systems
  - Pender et al (2020). Cornell University
    - → Different charging method

No research on efficient management of gig economy-based operation of charging e-scooters

# Combinatorial auction bundling

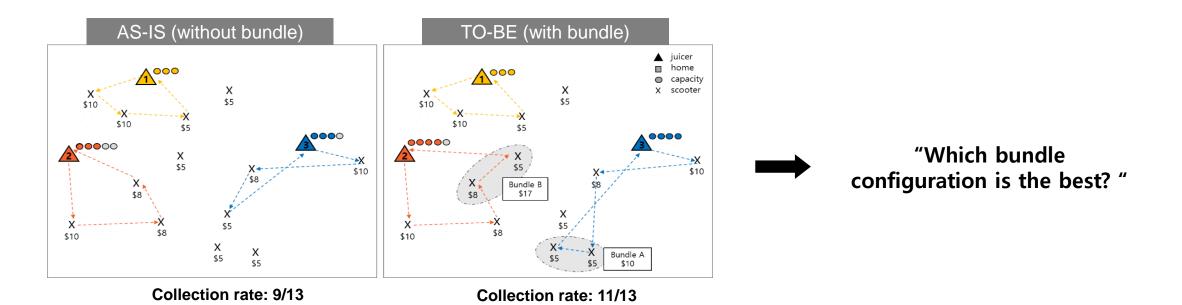
- Bidding strategy of combinatorial auction
   An et al. (2005). Journal of Revenue and Pricing Management
- Scale and density discount of package
   Olivares et al. (2012) : Management Science
- Transportation service procurement
   Song et al (2020). Transportation Research Record

Valuation of bidders toward package of items from cost synergies



Bundling strategy to increase collection rate of scooters

# In this thesis...



- $\rightarrow$  Provide bundle of scooters as an alternative to collect
- $\rightarrow$  Promote juicers' collection activity when a company cannot directly manage workers

### Objective

Create optimization-based bundling strategy to increase collection rate of scooters

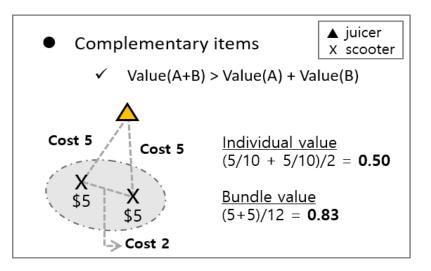
# 2. Problem Statement

### Combinatorial auction

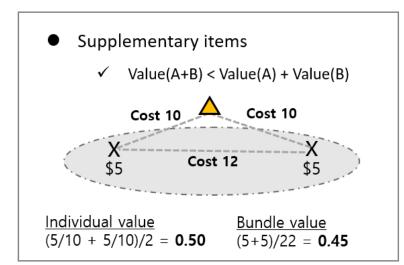
 $\rightarrow$  participants can place bids on combinations of items rather than individual items

#### 2 properties of a bundle

1. A person's value of getting items together as a package is greater than the sum of values for each item individually



 A person's value of getting items together as a package is less than the sum of values for each item individually



### Juicer system

- $\rightarrow$  Juicers start collection all together at predetermined time.
- $\rightarrow$  Juicers do not know other juicer's location or status.
- $\rightarrow$  Maximum number of reservations is limited to one scooter or one bundle.
- → Partial collection of a bundle is allowed; scooters in a bundle can be collected individually not as whole.

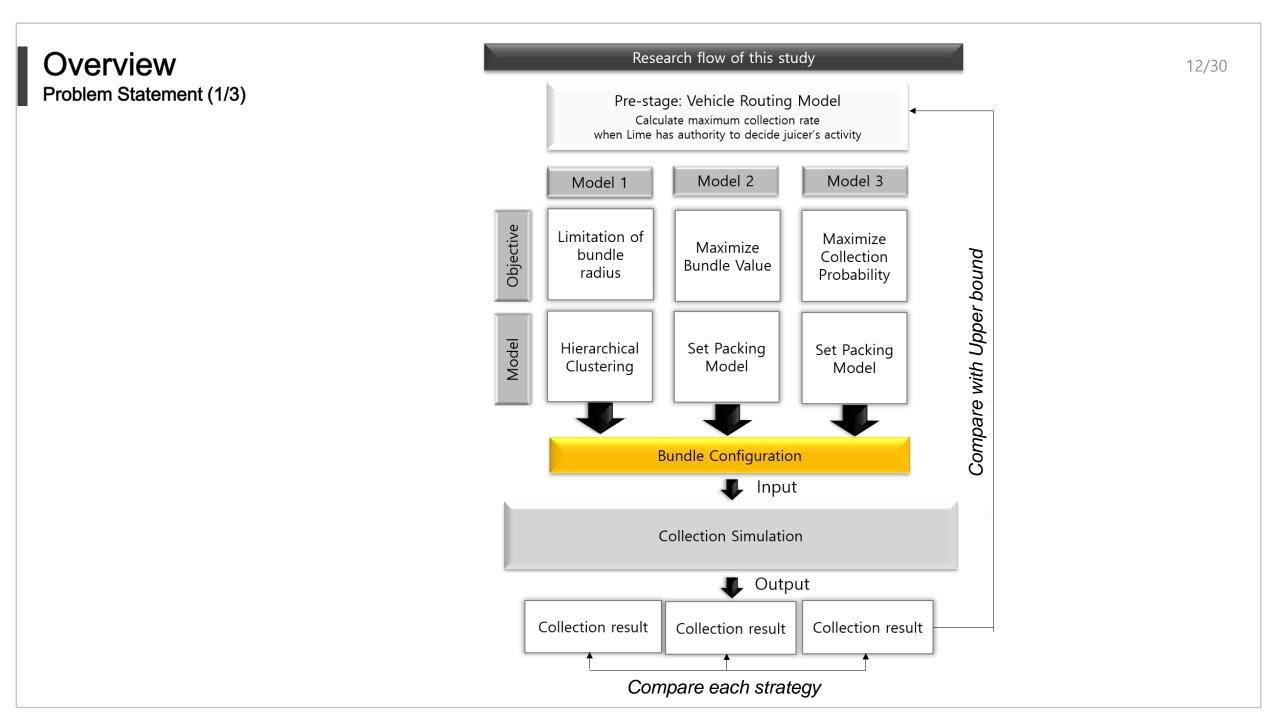
#### Juicer capacity

- $\rightarrow$  Juicers cannot charge more than the total charge amount possible with the chargers at home.
- $\rightarrow$  Juicer's capacity is equal.

### Juicer behavior

- $\rightarrow$  Once the juicer completes the collection and return home, the collection activity that day is over.
- → Juicer collects **the most valuable scooter or bundles**, which offer the highest profit per distance to collect and return home.

 $\rightarrow$  If juicer achieves the target amount (e.g. collected half of chargers), they only collect scooters of which value is more than certain criterion.



# 3. Mathematical Models

# Pre-stage Model

Mathematical Models (1/8)

## Multi depot capacitated VRP

- Assumes that the company can control the juicers to pick up allocated scooters
- Calculate maximum collection rate of given scooter/juicer data

### Sets

- N : Set of scooter nodes
- *K* : Set of juicer nodes (= depot nodes)
- V : Set of nodes  $(= N \cup K)$
- $\Pi$  : Set of arcs which violates relationship of juicer and depot

### **Decision Variables**

- $x_{ij}^k$ : 1, if juicer k made collection from scooter i to j 0, otherwise
- $u_i^k$ : Juicer k's filled capacity in after collecting scooter i

### Parameters

- *M* : Large number
- r : Small number
- *Q* : Juicer's capacity of possible amount to charge battery
- β : Threshold value of capacity filled by juicer where juicer satisfied expected amount of reward
- α : Baseline value of scooter (=profit/distance to reach and go back home) when juicer's filled capacity is over β
- $p_i$  : Collection price of scooter j
- $q_i$  : Battery that needs to be charged of scooter j
- $A[i, k, \alpha]$ : Set of scooters *j* of which value is under  $\alpha$  when juicer *k*'s capacity is over  $\beta$ % after collecting scooter *i*

#### **Pre-stage Model** 15/30 Mathematical Models (2/8) Multi depot capacitated VRP $Max \quad \sum_{i \in V} \sum_{j \in V, i \neq j} \sum_{k \in K} (1 - r * p_j) * x_{ij}^k$ Maximize the number of collected scooters while lowering the cost of the sum of collection price (7) $u_i^k = 0, \quad \forall i \in K, \forall k \in K, i = k$ Filled capacity in depot is zero (1) $x_{ij}^k = 0$ , (i, j, k) $\in \Pi$ Remove juicer-depot violation (8) $u_i^k + q_j \leq u_i^k + M(1 - x_{ij}^k), \quad \forall i \in V, \forall j \in N, \forall k \in K, i \neq j$ Capacity update (2) $\sum_{i \in N} x_{ki}^k = 1, \quad \forall k \in K$ Only travels once (9) $u_j^k \leq \left(\sum_{p \in V, p \neq j} x_{pj}^k\right) * M, \quad \forall j \in N, \forall k \in K$ Capacity is positive (3) $\sum_{i \in N} x_{ik}^k = 1$ , $\forall k \in K$ only when juicer visited Balance equation (10) $u_i^k - Q * \beta \le M * (1 - x_{ij}^k), \quad \forall i \in V, \forall k \in K, \forall j \in A[i, k, \alpha]$ (4) $\sum_{p \in V, p \neq i} x_{pi}^k = \sum_{t \in V, t \neq i} x_{it}^k$ , $\forall i \in N, \forall k \in K$ Juicer behavior constraint (11) $x_{ii}^k \in \{0,1\}, \forall i, j \in V, \forall k \in K$ Scooter can be (5) $\sum_{i \in V, i \neq j} \sum_{k \in K} x_{ij}^k \leq 1, \quad \forall j \in N$ collected by one juicer maximum or (12) $u_i^k \ge 0$ , $\forall i \in V, \forall k \in K$ (6) $\sum_{i \in V, i \neq i} \sum_{k \in K} x_{ii}^k \leq 1, \quad \forall i \in N$ not visited at all

# Pre-stage Model Mathematical Models (3/8)

(10)

#### Juicer behavior constraint

$$u_i^k - Q * \beta \le M * (1 - x_{ij}^k), \qquad \forall i \in V, \forall k \in K, \forall j \in A[i, k, \alpha]$$

precomputed

Contains scooters j which are impossible to collect when juicer collected scooter i and k's filled capacity is over  $\beta\%$  of the maximum capacity

Juicer behavior assumption

If a juicer collects more than  $\beta$ % of the maximum capacity,

only the scooters that are worth more than  $\alpha$  will be collected

Value of scooter (node) j from scooter (node) i $= \frac{\text{Price of scooter j}}{\text{Distance from node i to j + Distance from j to depot}}$ 

# Pre-stage Model Mathematical Models (4/8)

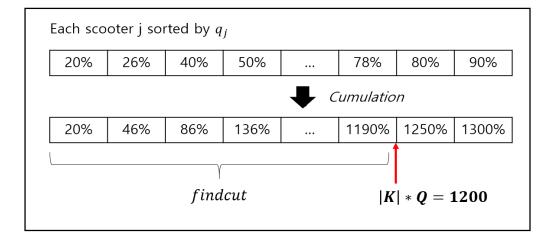
#### Cut constraint

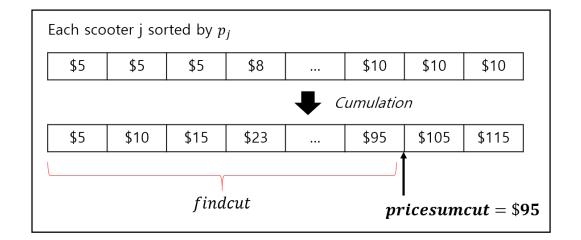
(13) 
$$\sum_{i \in V} \sum_{j \in V, i \neq j} \sum_{k \in K} x_{ij}^k \leq findcut + |K|$$

Upper bound of the number of collected scooters

(14) 
$$\sum_{i \in V} \sum_{j \in V, i \neq j} \sum_{k \in K} \left( 1 - r * p_j \right) * x_{ij}^k \leq findcut + |K| - r * pricesumcut$$

Upper bound of objective function considering price sum of collected scooters

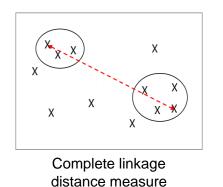


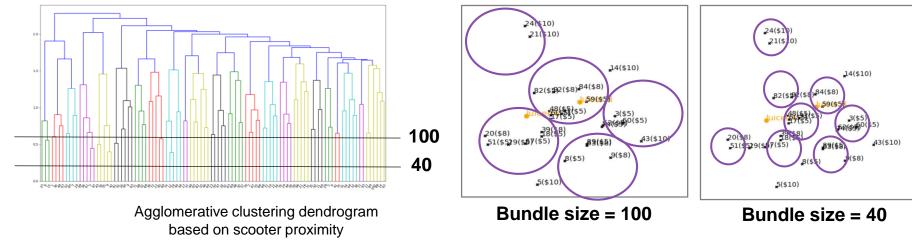


# Three types of bundling model (1) Mathematical Models (5/8)

#### Model I – Limiting cluster size

- Generate bundle of scooters with high proximity
- Create bundles with complementary properties
- Limitation of bundle size with a predetermined radius

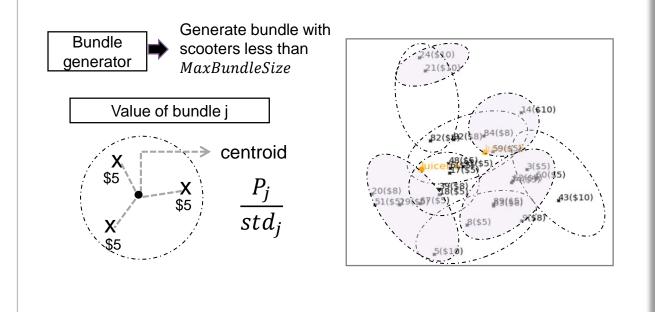


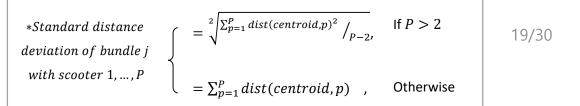


# Three types of bundling model (2) Mathematical Models (6/8)

### Model $\Pi$ – Maximize the sum of bundle value

- ldea
  - ✓ Generate bundle candidates with nearby scooters
  - ✓ Select winning bundles by Set packing model





#### (MD 2) Set Packing Model

 $x_i$ 

$$Max \quad \sum_{j \in \mathbf{B}} (\frac{P_j}{std_j}) x_j$$

s.t 
$$\sum_{j \in B} a_{ij} x_j \leq 1$$
,  $i \in N$   
 $x_j \in \{0, 1\}$ ,  $j \in B$ 

Maximize bundle value

Each scooter should be included in only one bundle

- : Binary decision variable  $\begin{cases}
  = 1, & \text{If bundle } j \in B \text{ is selected as winning bundle} \\
  = 0, & \text{Otherwise}
  \end{cases}$
- $P_j$  : Price of bundle j (= sum of scooter price in the bundle j)
- $std_i$  : Standard distance deviation of scooters in bundle j \*
- $a_{ij} \subseteq 1$ , If bundle  $j \in B$  contains scooter  $i \in N$ 
  - = 0, Otherwise

\*Levine, Ned. "CrimeStat III: a spatial statistics program for the analysis of crime incident locations (version 3.0)." Houston (TX): Ned Levine & Associates/Washington, DC: National Institute of Justice (2004).

# Three types of bundling model (2)

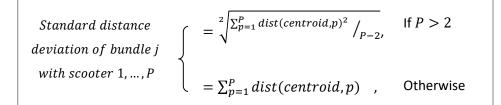
Mathematical Models (7/8)

INPUT

PROCEDURE

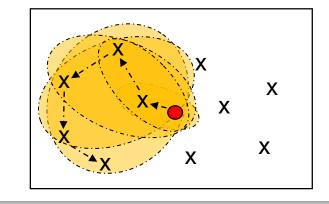
**Bundle generator** 

scooter node  $\forall i \in \mathbb{N}$ 



#### 1. Near pack generator

Generate bundles by adding nearest scooter to the last added scooter



# 2. Node pack generator

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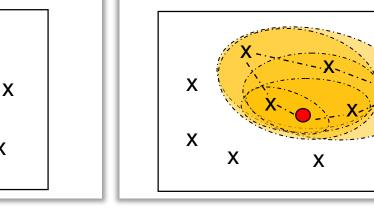
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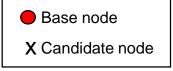
Generate bundles by adding the nearest scooters one by one depending on the distance from the base node

Х

#### 3. STD pack generator

Generate bundles by adding the scooter which increases the standard distance deviation to the smallest





Х

Result bundle = 1. + 2. + 3.OUTPUT

# Three types of bundling model (3) Mathematical Models (8/8)

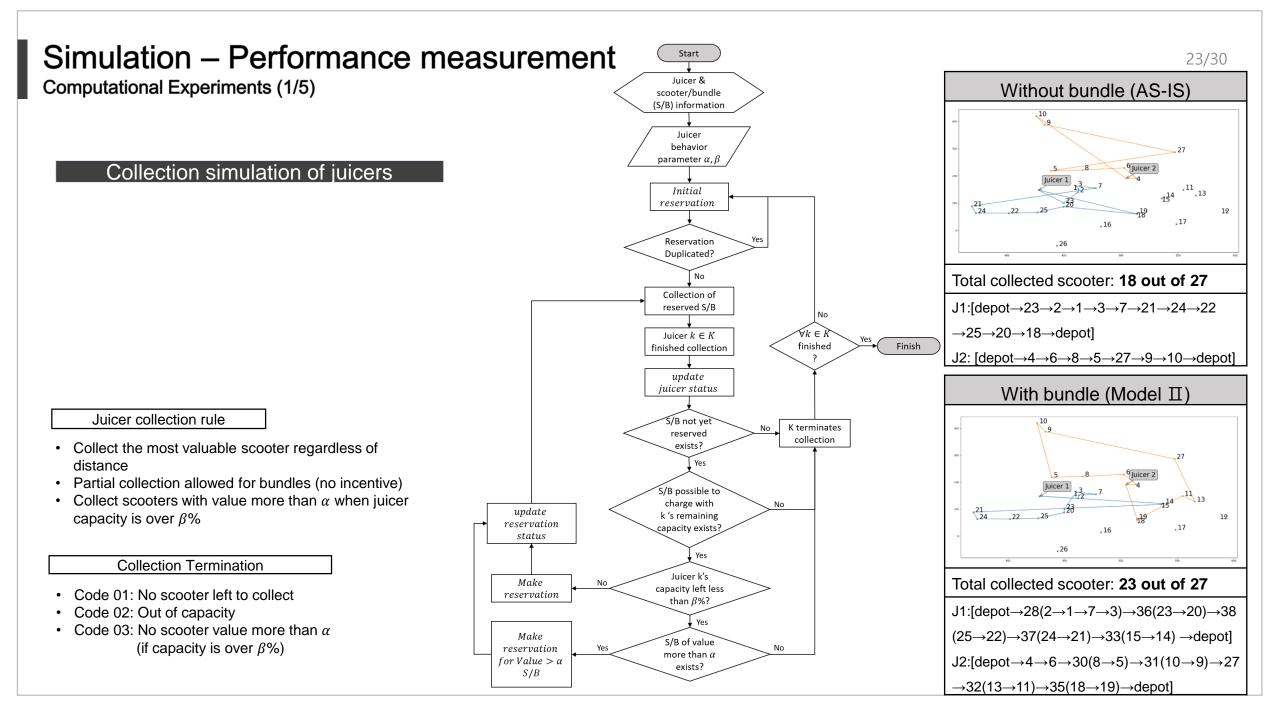
### Model III – Maximize the sum of probability of collection

- Idea
  - Select bundle configuration of which collection probability sum is maximized
  - ✓ Generate bundle candidates with bundle generator
  - ✓ Select winning bundles by Set packing model

Pr(k i)	$\begin{cases} = \exp(-\lambda * dist(k, j)/V_j), \\ = 0, \end{cases}$	If $dist(k, j) \leq \delta$
	l = 0,	Otherwise
λ	: decay coefficient	
δ	: distance limitation parameter	
dist(k,j)	: distance between juicer k's depot	and central point of bundle j
	$\Pr(j) = 1 - \prod_{k \in K} (1 - 1)$	$\Pr(k, j)$

	21/30
(MD 3) Set Packing Model	
$Max  \sum_{j \in B} (\Pr(j) - \gamma * Incentive_j) x_j$	Maximize collection probability
s.t $\sum_{j \in \mathbf{B}} a_{ij} x_j \leq 1$ , $i \in N$	Each scooter should be included in only one bundle
$\sum_{j \in B} Incentive_j x_j \leq Budget$	Total incentive cannot exceed
$x_j \in \{0,1\}, \qquad j \in \mathbf{B}$	Budget
<i>x<sub>j</sub></i> : Binary decision variable	
$\begin{cases} = 1, & \text{If bundle } j \in B \text{ is selected} \\ = 0, & \text{Otherwise} \end{cases}$	
Pr(j) : Probability of bundle j being co	
<i>Incentive</i> <sub>j</sub> : incentive provided for suppleme	ent bundle according
to bundle incentive rate	
Budget : Budget for incentive	
$\gamma$ : coefficient	
$a_{ij} \int = 1$ , If bundle $j \in B$ contains	scooter $i \in N$
= 0,  Otherwise	

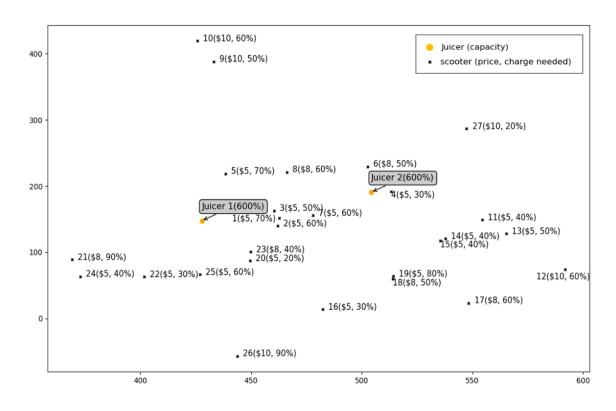
# 4. Computational Experiments



# Description of parameters

Computational Experiments (2/5)

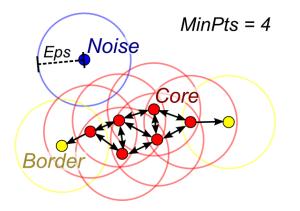
# • test instance of 2 juicers and 27 scooters



Description of data generation

		Value	Method
	Price	\$5, \$8, \$10	DBSCAN clustering
Scooter	Battery level	10%~80%	Selected randomly
Juicer	Capacity	600%	Fixed
	α	0.03	Fixed
	β	0.5	Fixed

 DBSCAN clustering (Density based spatial clustering of applications with noise)



✓ Core: \$5

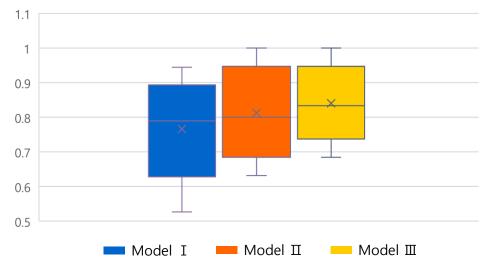
- ✓ Border: \$8
- ✓ Noise: \$10

MinPts = 3, Eps = 60

# Pre-model vs bundling model

Clustered scooter(#) : Randomly located scooter(#)	Total scooter(#)	Total juicers
15 : 5	20	2

Collection simulation result compared with pre-model (small data set)

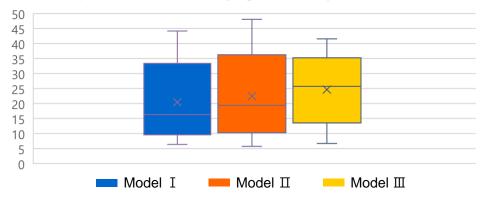


# Results Computational Experiments (4/5)

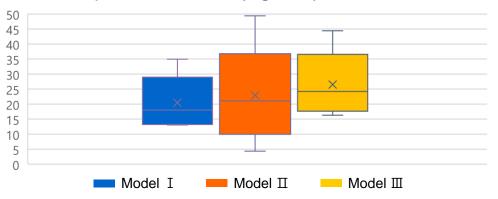
# AS-IS vs Model

Scenario	Clustered scooter(#) : Randomly located scooter(#)	Total scooter(#)	Total Juicers
I	120 : 30	150	10
	80 : 70	150	10

Collection simulation result compared with AS-IS (big data set) - Scenario I



Collection simulation result compared with AS-IS (big data) – Scenario  ${\rm I\!I}$ 



# Results Computational Experiments (5/5)

# Juicer status

Scenario	Clustered scooter(#) : Randomly located scooter(#)	Total scooter(#)	Total Juicers
I	120 : 30	150	10
	80 : 70	150	10

#### Juicer information - Scenario I

Scenario I (120:30)	AS-IS	Model I	Model II	Model III
Achievement rate(%)	62.5333	73.4083	74.9292	77.1417
Total distance(10m)	1038.6482	991.4776	1080.9820	1098.6147
Profit(\$)	64.6067	69.7500	72.8667	73.8549
Margin	54.2202	59.8352	62.0568	62.8688

### Juicer information - Scenario II

Scenario II (80:70)	AS-IS	Model I	Model II	Model III
Achievement rate(%)	60.9458	72.3750	73.9875	76.3000
Total distance(10m)	1165.1820	1074.5587	1210.7677	1191.5665
Profit(\$)	72.0667	76.2900	81.3600	82.4004
Margin	60.4148	65.5444	69.2523	70.4847

# 5. Conclusion

# Conclusion

### Contribution

- Research on gig economy-based scooter charging operation
- Proposed three bundling models to improve collection rate of scooters
- Provided efficient strategy for both the company and juicers
  - $\rightarrow$  For Lime (Company)
    - ✓ Lowering cost of recharging, increasing competitive advantage
    - ✓ Help to control proportion of juicer and Lime's full-time worker and induce juicers to join the community
  - $\rightarrow$  For Juicer (Gig worker)
    - ✓ Lower uncertainty of juicers from competition by providing bundles and helping juicers to plan their route
    - ✓ Assist juicers to obtain higher margin

# 감사합니다